Mechanics of **Materials Labs** with SolidWorks Simulation 2014



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Chapter I Stresses

Stresses are quantities to describe the intensity of force in a body (either solid or fluid). Its unit is force per unit area (i.e., N/m^2 in SI). It is a position-dependent quantity.

Imagine that your arms are pulled by your friends with two forces of the same magnitude but opposite directions. What are the stresses in your arms? Assuming the magnitude of the forces is 100 N and the cross-sectional area of your arms is 100 cm², then you may answer, "the stresses are 1 N/cm². everywhere in my arms." This case is simple and the answer is good enough. For a one-dimensional case like this, the stress σ may be easily defined as

$$\sigma = \frac{P}{A}$$

where *P* is the applied force and *A* is the cross sectional area.

In general 3D cases, things are much more complicated. Now, imagine that you are buried in the soil by your friends, and your head is 100 meters deep below the ground surface. How do you describe the force intensity (i.e., stress) on your head?

If the soil is replaced by still water, then the answer would be much simpler. The magnitude of the pressure (stress) on the top of your head would be the same as the pressure on your cheeks, and the direction of the pressure would always be perpendicular to the surface where the pressure applies. You've learned these concepts in your high school. And you've learned that the magnitude of the pressure is $\sigma = \rho gh$, where ρ is the mass density of the water, g is the gravitational acceleration, and h is the depth (100 meters in this case). In general, to describe the force intensity at a certain position in water, we place an infinitesimally small body at that position, and measure the force per unit surface area on that body.

In the soil (which is a solid material rather than water), the behavior is quite different First, the magnitude of the pressure on the top of your head may not be the same as that on your cheeks. Second, the direction of pressure is not necessarily perpendicular to the surface where the pressure applies. However, the above definition of stresses for water still holds. Let me restate as follows:

The stress at a certain position in a solid material is defined as the force per unit surface area on an infinitesimally small body placed at that position.

Note that the infinitesimally small body could be any shapes. However, if we know the stresses on a certain shape of small body, we can infer the stresses on other shapes. We usually take a small cube to describe the stresses.

This chapter will guide you to learn the concepts of stresses.

Section I.I

Stress Components

I.I-I Introduction

[1] Consider a cantilever beam made of an alloy steel and of dimension 10 mm x 20 mm x 100 mm [2], which is fixed at one end [3] and subjected to a force on the other end [4]. The force is in positive X-direction and has a magnitude of 10,000 N. Note that we've used a reference coordinate system as shown in [5].

In theory, the stress is uniform over the body; i.e., every point in the beam has the same stress. How do we describe this stress? Can we simply say, the stress is 50 MPa, which is calculated by

 $\frac{10,000 \text{ N}}{10 \text{ mm} \times 20 \text{ mm}} = 50 \text{ MPa}?$

For a simple case like this, that may be adequate. In order to apply to more general cases, we need to say something more, specifically, what is the direction of the stress? What is the surface on which the stress acts?



[6] Definition of Stress

The stress at a certain point can be defined as the force per unit area acting on the boundary surfaces of an infinitesimally small body centered at that point [7]. The stress values may be different at different locations of the boundary surfaces. The small body can be any shape. However, for the purpose of describing the stress, we usually use a small cube [8] of which each edge is parallel to a coordinate axis. If we can find the stresses on a small cube, we then can calculate the stresses on any other shapes of small body (see [18]).

[9] X-Face, Y-Face, and Z-Face

Each of the six faces of the cube can be assigned an identifier as X-face, Y-face, Z-face, negative-X-face, negative-Y-face, and negative-Z-face, respectively [10-13].

[14] Stress Components

Let \vec{p}_x be the force per unit area acting on the X-face. In general, \vec{p}_x may not be normal or parallel to the X-face. We may decompose \vec{p}_x into X-, Y-, and Zcomponent, and denote σ_{xx} , τ_{xy} , and τ_{xz} respectively [15]. The first subscript (X) is used to indicate the **face** on which the stress components act, while the second subscript (X, Y, or Z) is used to indicate the **direction** of the stress components. Note that σ_{xx} is normal to the face, while τ_{xy} , and τ_{xz} are parallel to the face. Therefore, σ_{xx} is called a **normal stress**, while τ_{xy} , and τ_{xz} are called **shear stresses**. In Mechanics of Materials, we usually use the symbol σ for a normal stress and τ for a shear stress.

Similarly, let \vec{p}_{γ} be the force per unit area acting on the Y-face and we may decompose \vec{p}_{γ} into a normal component ($\sigma_{\gamma\gamma}$) and two shear components ($\tau_{\gamma\chi}$ and $\tau_{\gamma\chi}$) [16]. Also, let \vec{p}_z be the force per unit area acting on the Z-face and we may decompose \vec{p}_z into a normal component (σ_{ZZ}) and two shear components (τ_{ZX} and τ_{ZY}) [17]. Organized in a matrix form, these stress components may be written as

$$\left\{ \sigma \right\} = \left(\begin{array}{ccc} \sigma_{XX} & \tau_{XY} & \tau_{XZ} \\ \tau_{YX} & \sigma_{YY} & \tau_{YZ} \\ \tau_{ZX} & \tau_{ZY} & \sigma_{ZZ} \end{array} \right)$$
 (1)



[18] Stress Components on Other Faces

It can be proven that the stress components on the negative-X-face, negative-Y-face, and negative-Z-face can be derived from the 9 stress components in Eq. (1). For example, on the negative-X-face, the stress components have exactly the same stress values as those on the X-face but with opposite directions [19]. Similarly, the stress components on the negative-Y-face have the same stress values as those on the Y-face but with opposite directions [20], and the stress components on the negative-Z-face have the same stress values as those on the Y-face but with opposite directions [21].

The proof can be done by taking the cube as free body and applying the force equilibria in X, Y, and Z directions respectively.

On an arbitrary face (which may not be parallel or perpendicular to an axis), the stress components also can be calculated from the 9 stress components in Eq. (1). We'll show that this can be done using Mohr's circles (Section 10.1).

[22] Symmetry of Shear Stresses

It also can be proven that the shear stresses are symmetric, i.e.,

$$\tau_{XY} = \tau_{YX}, \quad \tau_{YZ} = \tau_{ZY}, \quad \tau_{ZX} = \tau_{XZ} \tag{2}$$

The proof can be done by taking the cube as free body and applying the moment equilibria in X, Y, and Zdirections respectively.

[23] Stress State

We now conclude that 3 normal stress components and 3 shear stress components are needed to describe the **stress state** at a certain point, which may be written in a vector form

$$\{\sigma\} = \left\{ \sigma_{X} \quad \sigma_{Y} \quad \sigma_{Z} \quad \tau_{XY} \quad \tau_{YZ} \quad \tau_{ZX} \right\} \quad (3)$$

Note that, for more concise, we use σ_x in place of σ_{xx} , σ_y in place of σ_{yy} , and σ_z in place of σ_{zz} .

The purpose of this section is to guide the students familiarize the 6 stress components in Eq. (3). The stress field in this section is uniform over the entire body. In the next section, we'll explore a nonuniform stress field.

Another purpose of this section is to familiarize the **SolidWorks Simulation** user interface.#





1.1-2 Launch SolidWorks and Create New Part

About the Text Boxes

1. Within each subsection (e.g., 1.1-2), text boxes are ordered with numbers, each of which is enclosed by a pair of square brackets (e.g., [1]). When you read the contents of a subsection, please follow the order of the text boxes. 2. The text box numbers are also used as reference numbers. In the same subsection, we simply refer to a text box by its number (e.g., [1]). From other subsections, we refer to a text box by its subsection identifier and the text box number (e.g., 1.1-2[1]).

3. A text box is either round-cornered (e.g., [1, 3, 5]) or sharp-cornered (e.g., [2, 4]). A round-cornered box indicates that **mouse or keyboard actions** are needed in that step. A sharp-cornered box is used for commentary only; i.e., mouse or keyboard actions are not needed in that step.

4. A symbol # is used to indicate the last text box of a subsection, so that you don't leave out any text boxes.

SolidWorks Terms

In this book, terms used in the **SolidWorks** are boldfaced (e.g., **Part** in [4, 5]) to facilitate the readability.#



I.I-4 Create Geometric Model





1.1-5 Load SolidWorks Simulation



I.I-6 Create a Static Structural Study





1.1-7 Set Up Options for SolidWorks Simulation





I.I-9 Apply Support



I.I-10 Apply Load





1.1-12 View the Normal Stress σ_{x}



1.1-13 View Other Stress Components

1.1-14 Save the Document and Exit SolidWorks

Location: 2 3, 7, 2 Location: 10,0 001 3,0 mm 51 253 N/mm 2 04P

Section I.2

More on Stress Components

I.2-1 Introduction

[1] In the last section, the stress field is uniform over the body and the only non-zero stress component is σ_{χ} . In this section, we'll use the same model in the last section [2-5] but add a uniformly distributed transversal pressure of 1.0 MPa on the upper face of the beam [6]. In this case, the resulting stress will not be uniform, and non-zero shear stress components exist in the beam.

This section also demonstrates a way to retrieve results at specific locations in a body, namely the **Section Clipping** method.

I.2-3 Add Transversal Load

1.2-4 Animate the Deformation

1.2-5 Create Section View

1.2-6 Stress Components at the Locations A and B

1.2-7 Distribution of σ_x Along Horizontal and Vertical Edges

1.2-8 Distribution of $au_{\rm XY}$ Along a Vertical Edge

Ρ

Section I.3

Stresses in a C-Bar

1.3-1 Introduction

[1] The C-shaped bar is made of an alloy steel and used as a dynamometer, a device to measure the magnitude of a force P [2]. A strain gauge is usually attached to the surface of a location as shown [3], and the measured strain is used to calculate the force P.

In this exercise, we will create a 3D solid model for the C-bar [4-6] and perform a static structural analysis under a force P = 2000 N. We'll examine the stress states at two locations, **A** [7, 8] and **B** [9, 10]. We examine location **A** since it is where the strain gauge situated and its normal stress σ_v is high. Location **B** is arbitrarily chosen for its non-zero shear stress τ_{xy} .

This section also demonstrates a way to obtain stress results at specific location, namely using **Sensors**.

[3] A strain

gauge is attached to

the surface

here. The

measured

strain is used

to calculate the force *P*.

I.3-2 Start Up

[1] Launch **SolidWorks** and create a new part. Set up **MMGS** unit system with zero decimal places for the length unit.#

1.3-3 Create a Sketch for the Sweeping Path

- I.3-4 Create a New Plane
- [I] In Features Toolbar, select **Reference** Geometry>Plane. Swept Boss/Base 388 Rib Wrap Swept Cut V Extruded Hole Revolved Lofted Cut Phone -R Reference Extruded Revolved 🖉 Lofted Boss/Base Boss/Base Boss/Base Fillet Linear Draft Dom Pattern Draft Dom urves Instant3D Geometry 💼 Boundary Boss/Base 👚 Boundary Cut Shell 🔄 Mirri Features Sketch Surfaces Weldments Mold Tools Data Migration Direct Editing Evaluate DimXpert Office Products

1.3-5 Create a Sketch for the Profile

1.3-6 Create a Solid Body Using Sweep

I.3-7 Create an Ear

1.3-10 Create Sensor at Location A

1.3-11 Create Sensor at Location B

1.3-12 Create a Static Structural Study and Set Up Unit System

1.3-14 Set Up Boundary Conditions and Run the Model

1.3-15 The Stresses at Location A

1.3-16 The Stresses at Location B

